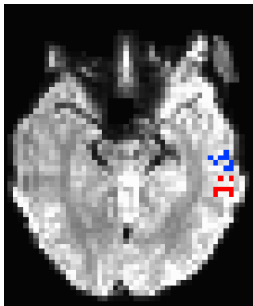
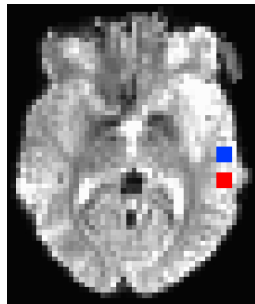


Variational Bayes for fMRI Data: Detecting Scattered Signal



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April 20, 2018



Project Goal

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- at detecting scattered signal
- in simulated functional magnetic resonance imaging (fMRI) data.

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- A natural consequence of these sorts of steps is that traditional analyses are very good at detecting clusters of activation.
- They are not designed to detect scattered (or patterns of) signal.

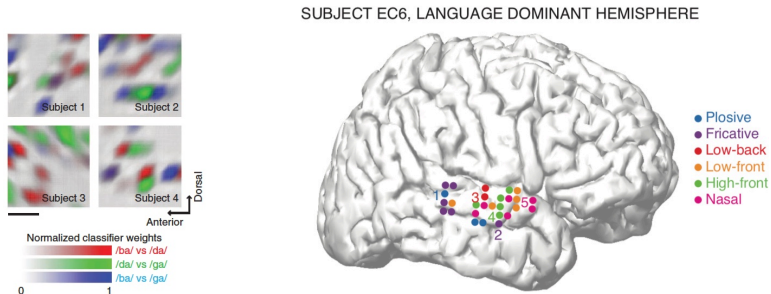
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Left image is from Chang et al. (2010, pg. 1431) and right from Mesgarani et al. (2014, supplemental material).

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- Much hope has been placed in classification analyses (k-Nearest Neighbors, support vector machines, etc.).
- However, many of these approaches have a variety of pitfalls, and
- personal work exploring the efficacy of a variety of these methods has not revealed one that reliably detects scattered signal.

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Bayesian methods...

- are highly flexible.
- can easily incorporate multiple sources of information (e.g. prior results, structural neurological information, etc.).
- can more easily incorporate spatial information into the primary analysis.

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- In order to better understand which aspects of a Bayesian approach would most effectively allow detection of scattered signal, I decided to explore some existing methodologies.
- Moreover, while quite complex Bayesian approaches to fMRI analyses exist in the literature, it felt appropriate to begin with a more simple approach.
- Penny, Kiebel, and Friston (2003) propose analyzing fMRI data with a voxelwise, autoregressive model estimated by Variational Bayes approximation.

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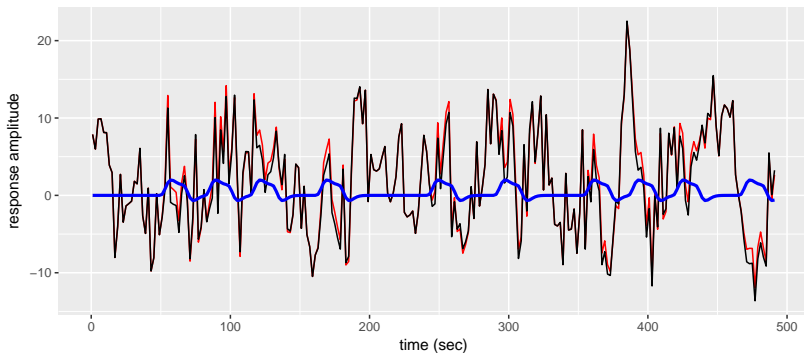
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- The data were simulated to have spatial and temporal autocorrelation.
- Two types of signal were simulated (/a/ and /i/).
- Each type was added to 27 randomly-chosen voxels.

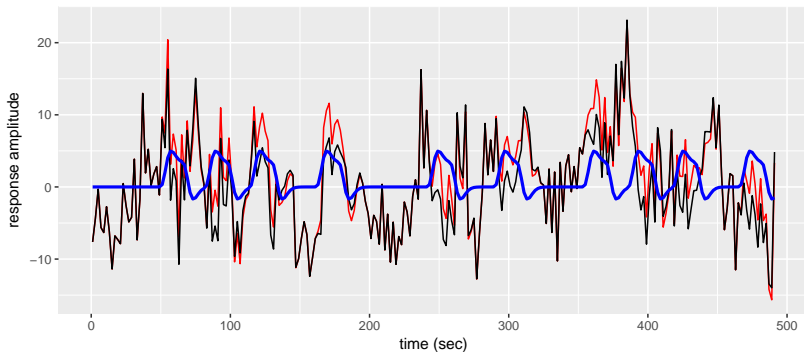
Signal-to-Noise Ratio: 2

Sample error (black), signal (blue), and signal + error (red)
in /a/-signal-containing voxel, signal-to-noise ratio: 2



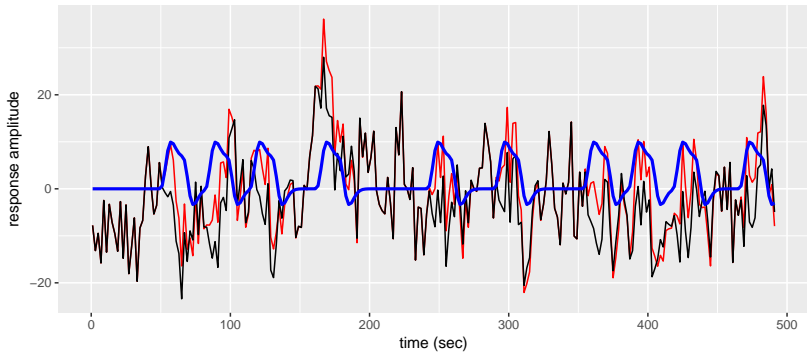
Signal-to-Noise Ratio: 5

Sample error (black), signal (blue), and signal + error (red)
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Signal-to-Noise Ratio: 10

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- The design matrix X contains an intercept column, a column for /a/ signal, and a column for /i/ signal.

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 - $p(\lambda) = \text{Gamma}(\ell_1, \ell_2)$, where $\ell_1 = 1000$ and $\ell_2 = 0.001$

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- It is often less computationally intensive than finding the true posterior.
- However, there are costs to using Variational Bayes:
 - It often underestimates variances.
 - It also often does a poor job at data correlation structure estimation.

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- Minimizing the KL divergence is the same as maximizing the negative variational free energy (F).

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- Because of this restriction, the maximum value of F is attained when the individual approximate posteriors are of specific parametric forms ($\beta|Y$ is normal, $\alpha|Y$ is normal, $\lambda|Y$ is gamma).
- The formula to calculate the parameters of each posterior distribution involves the other posteriors. Thus, iterated application of the formulas is used until a previous value of F and a current value are within a preset tolerance.

Results

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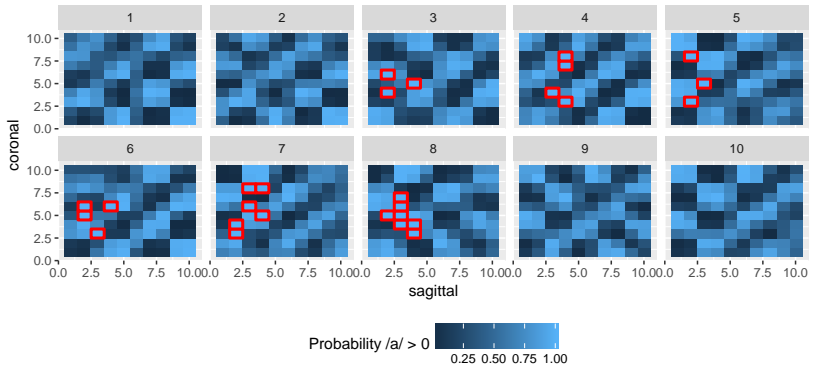
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- For each dataset, the approximate posteriors are estimated separately.
- For each dataset, the probability that the coefficient associated with /a/ signal is greater than 0 is calculated.
- The same is done for /i/.
- Results from the two conditions are similar; the next plots thus just depict $P(/a/ \text{ coefficient} > 0)$.

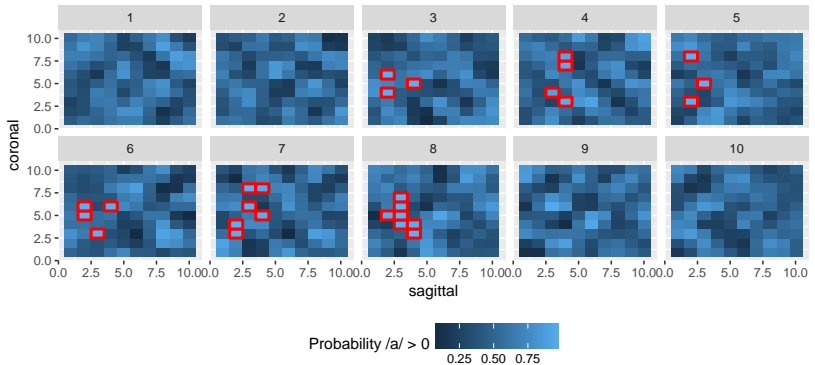
Signal-to-Noise Ratio: 10

$P(a > 0)$ per Voxel for SNR 10



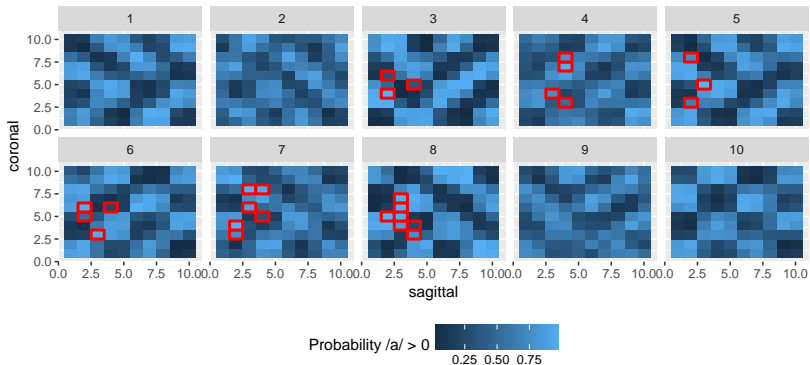
Signal-to-Noise Ratio: 5

$P(|a| > 0)$ per Voxel for SNR 5



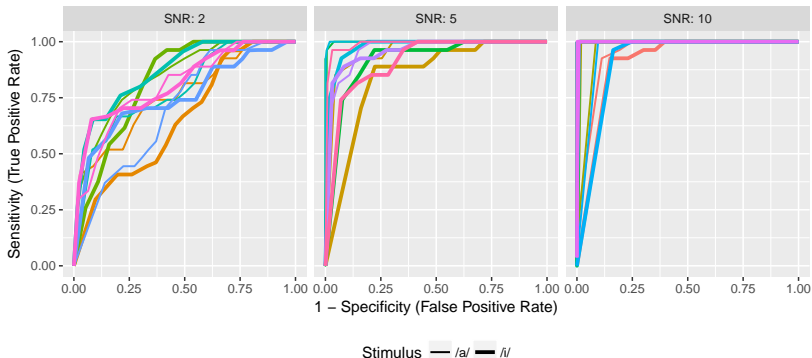
Signal-to-Noise Ratio: 2

$P(a > 0)$ per Voxel for SNR 2



Receiver Operating Characteristic Curves

Sensitivity by Specificity for Various Datasets and Conditions



Conclusions

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- For the more realistic low signal-to-noise condition, the algorithm did not perform very well.
- More algorithms need to be explored.
- (Carefully!) capitalizing on spatial information may help.

Many thanks to...

- Ed Bedrick
- Dean Billheimer
- All of you!

References

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The Noise Base

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- To approximate the temporally autocorrelated noise present in fMRI data, 1000 independent timecourses were simulated from the model $e_t = \tilde{e}_t \alpha + z_t$, where

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 - $B = (I - 0.3W)^{-1}\epsilon$

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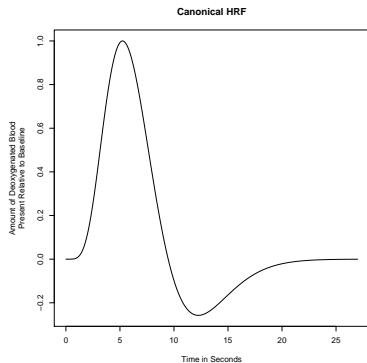
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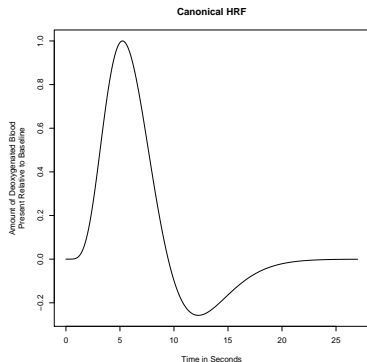
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 - Two types of stimuli (say the vowels /a/ and /i/) presented in 16-second blocks
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- When a stimulus is presented to a part of the brain that cares about it, the ratio of oxygenated to deoxygenated blood has a (fairly) predictable response — the hemodynamic response function (hrf).

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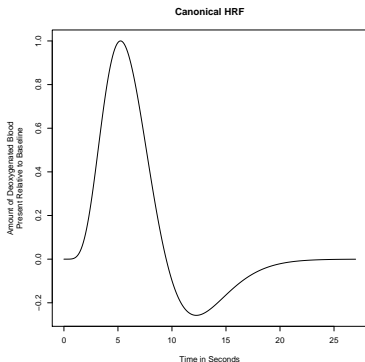


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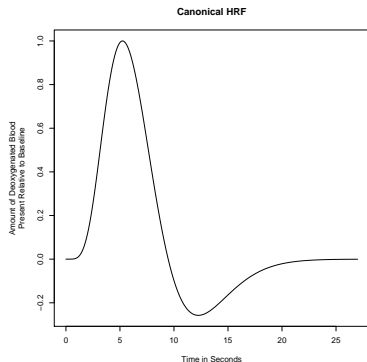
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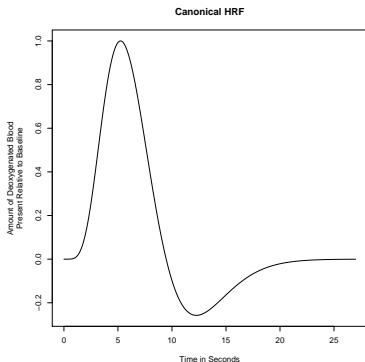
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- The simulated timecourses are scaled to have maxima of 2, 5, or 10 (the signal-to-noise ratio conditions).
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- 5 datasets are simulated per condition.

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- The $\hat{\beta}$ associated with a given predictor represents the extent to which a given voxel responded to that predictor.